



What can we expect from grid point AROME ?

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Problem

Two issues :

- Scalability
- Steep slopes

A common solution ?

- Grid Point approach



AROME 2D - presentation

- ICI constant coefficient, SL, A-grid, mass-based coordinate, etc
- No physics, idealised test cases
- Spectral or grid point versions

Grid point version :

- Explicit diffusion
- Krylov solver

Stop criterion :

$$\varepsilon = \frac{\sqrt{(Ax - b)^T (Ax - b)}}{\sqrt{bb^T}}$$



Density current test case

Spectral vs Grid Point 4th order, $N_{iter} \approx 10$



Hypothesis

Parallelisation :

- No MPI, no Open-MP

Geometry :

- 500 x 500 pts (vs 1536 x 1440 pts in operational AROME)

Spectral computations :

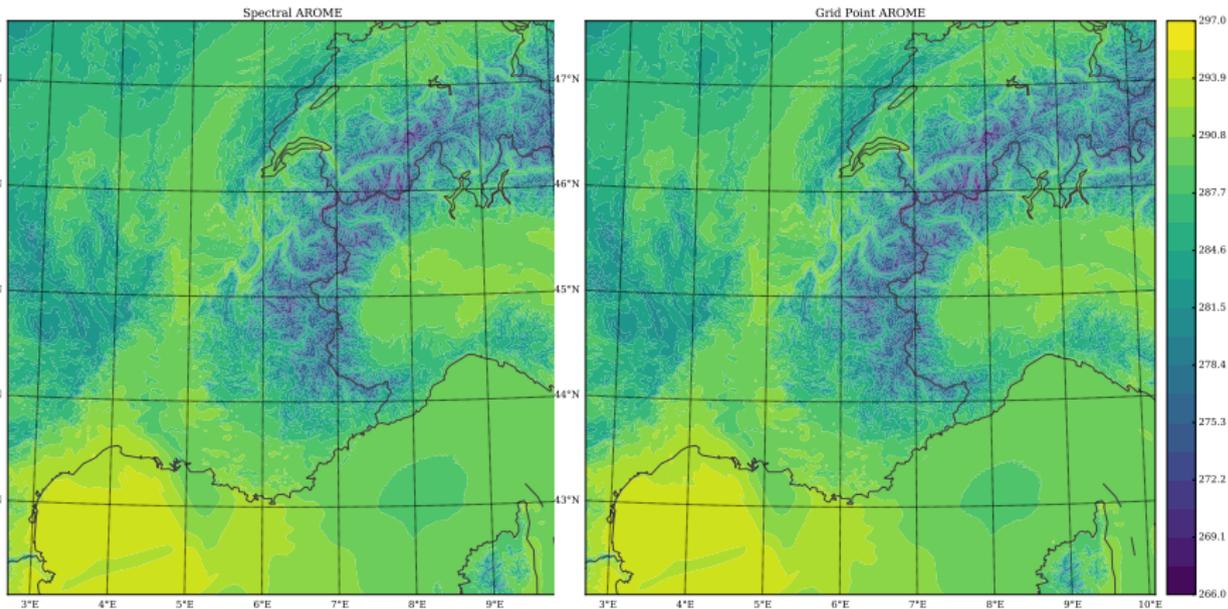
- From $D^{t+\Delta t}$ to $U^{t+\Delta t}$ and $V^{t+\Delta t}$
- Implicit diffusion
- RHS

Grid point computations :

- Derivatives in the linear operator
- Krylov solver



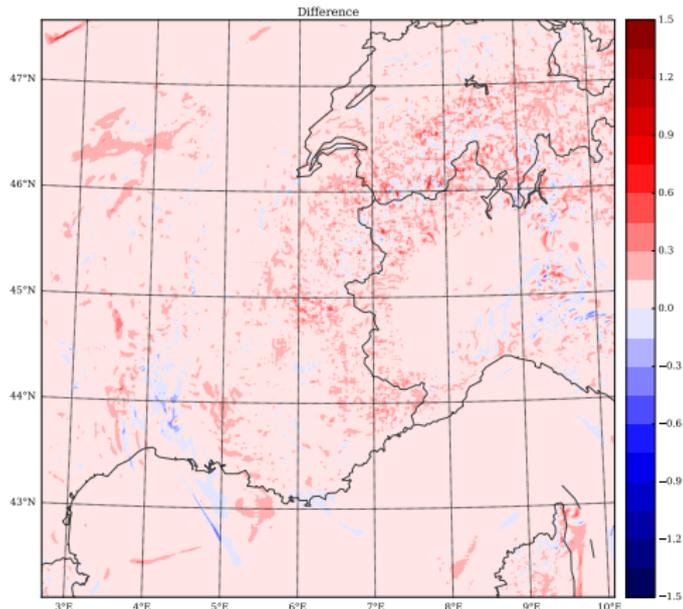
Spectral vs Grid Point



$T80$, $\delta t = 50$ s, $T = 2$ h, $\Delta x = 1.3$ km, $N_{iter} \approx 13$, 8th order



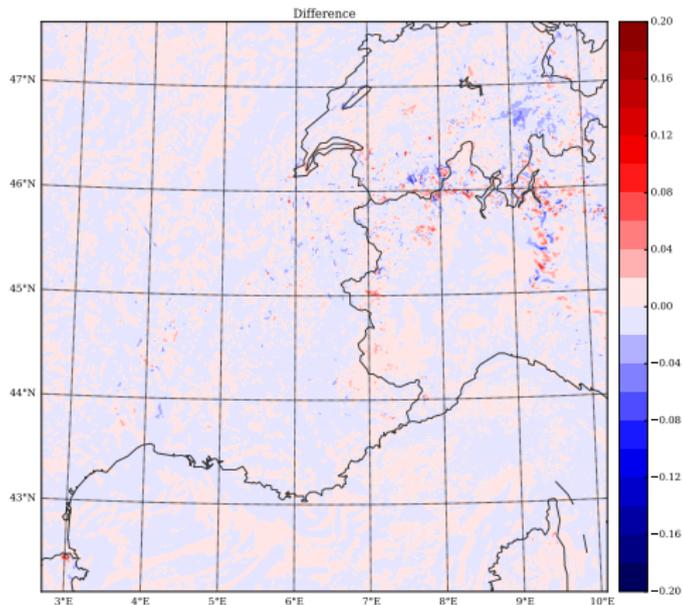
Spectral vs Grid Point



$\delta(T80)$, $\delta t = 50$ s, $T = 2$ h, $\Delta x = 1.3$ km, $N_{iter} \approx 13$, 8th order



Sensitivity test case

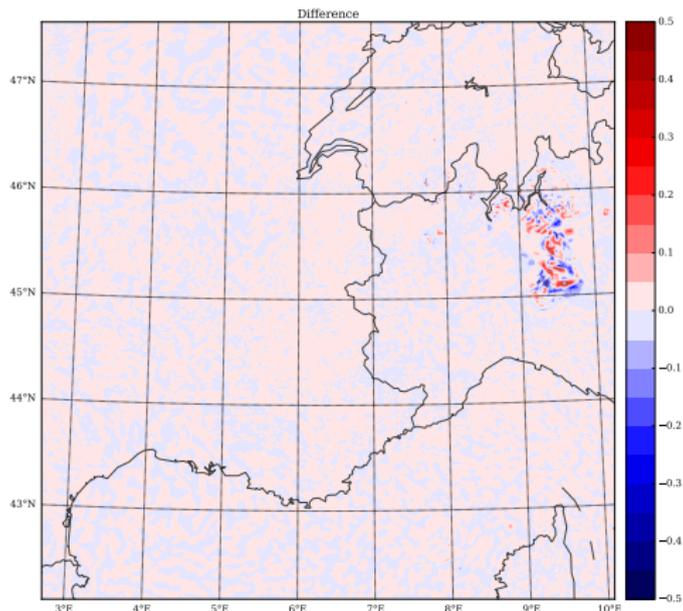


$\delta(T80)$, $\delta t = 50$ s, $T = 2$ h, $\Delta x = 1.3$ km

One more iteration in the ICI



Sensitivity test case



$\delta(T80)$, $\delta t = 50 \text{ s}$, $T = 2 \text{ h}$, $\Delta x = 1.3 \text{ km}$

Random noise at the bottom of the atmosphere ($\sigma = 0.01 \text{ K}$) at $t = 0$



Comparisons

- Comparisons between AROME and some observations : nearly identical scores after 4 hours (not shown)

Perspectives :

- To extend study to 8 * 24 hours forecast



Solver for constant coefficient SI

$$\left[1 - \delta t^2 \mathbf{B} \Delta\right] D^{t+\delta t} = D^{\bullet\bullet}$$

B non-symmetric matrix (boundary conditions) : GMRES method



Solver for constant coefficient SI

By projecting in the eigenspace of \mathbf{B} :

$$\left[1 - \delta t^2 b_m \Delta\right] QD^{t+\delta t} = QD^{t}$$

where $b_m \in [10^{-2}, 10^5] \text{ m}^2 \text{ s}^{-2}$

$(\sqrt{b_m} \in [0.1, 320] \text{ ms}^{-1})$



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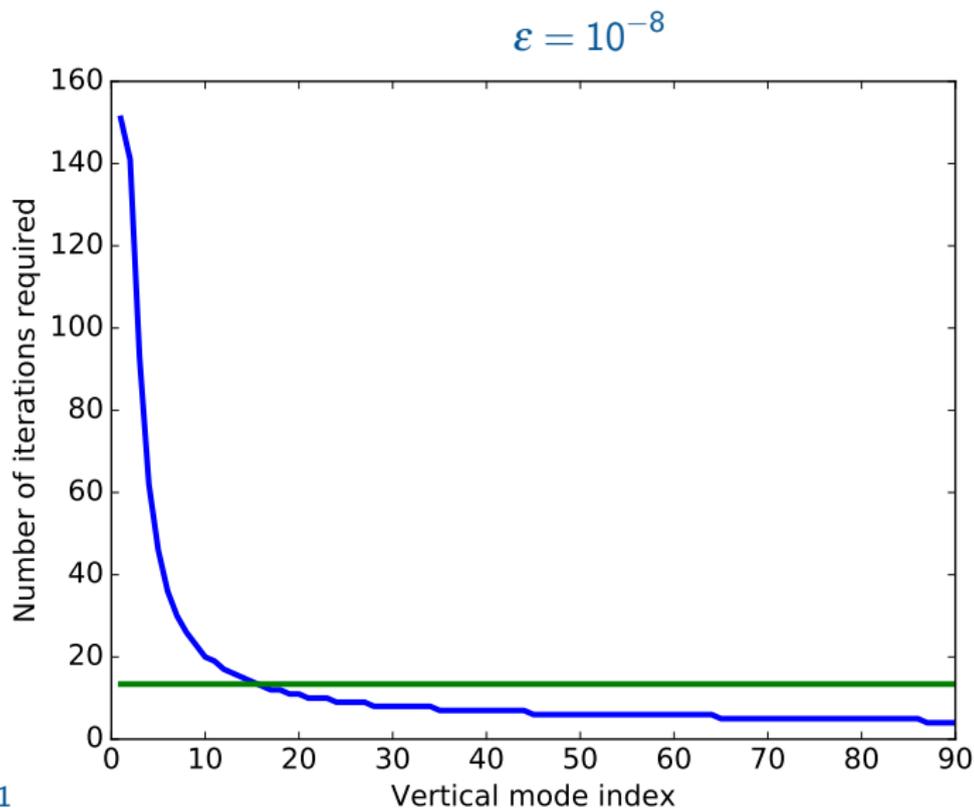
($\sqrt{b_m} \in [0.1, 320] \text{ ms}^{-1}$)

$$\text{cond} \approx \frac{1 + \Delta t^2 b_m \pi^2 / \Delta x^2}{1 + \Delta t^2 b_m 4\pi^2 / L^2} \approx 1 + \delta t^2 b_m \frac{\pi^2}{\Delta x^2} = 1 + C_*^2$$

where C_* is the CFL number



Convergence behaviour





Numerical cost

AROME operational configuration (2019)

- 170 nodes on Bull SX supercomputer
- **output bandwidth from a node : 7 Go/s**
- network latency : 0.864 ms



Numerical cost

AROME operational configuration (2019)

- 170 nodes on Bull SX supercomputer
- **output bandwidth from a node : 7 Go/s**
- network latency : 0.864 ms

Without projection on vertical modes (150 iterations required) :

"Total" cost : $27.5 + 0.1 \approx 27.6$ s

With projection on vertical modes (13 iterations required) :

"Total" cost : $2.4 + 1 \approx 3.4$ s



Comparison with an HEVI model

Cost of 1 iteration in the solver \approx Cost of 1 acoustic time step



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Cost of 1 iteration in the solver \approx Cost of 1 acoustic time step

$$\delta t = 50 \text{ s}, \Delta x = 1300 \text{ m}, c = 350 \text{ m/s}$$

HEVI model (if we suppose $CFL < 1$) :

$$\Delta t \approx 4 \text{ s}$$



Comparison with an HEVI model

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HEVI model (if we suppose $CFL < 1$) :

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SI grid point model :

$$\Delta \tau = \frac{\delta t}{2N_{iter}} = \frac{50}{2 * 13} \approx 2 \text{ s}$$



Conclusion

Results

- Non exact derivatives \rightarrow Order ≥ 6
- Convergence $\rightarrow N_{iter} \approx 13$
- Technical viability
- Simulated computational cost seems low



Linear equations without orographic terms

$$\frac{\partial U'}{\partial t} = -RT^* \frac{\partial q'}{\partial x} - \frac{RT^*}{\pi_S^*} \frac{\partial \pi'_S}{\partial x} - R \int_{\eta}^1 \frac{m^*}{\pi^*} \frac{\partial T'}{\partial x} d\eta' + RT^* \int_{\eta}^1 \frac{m^*}{\pi^*} \frac{\partial q'}{\partial x} d\eta'$$

$$\frac{\partial d'}{\partial t} = -\frac{g}{rH^*} \partial^* (\partial^* + 1) q'$$

$$\frac{\partial q'}{\partial t} = -\frac{C_p}{C_v} \left(\frac{\partial U'}{\partial x} + d' \right) + \frac{1}{\pi^*} \int_0^{\eta} m^* \frac{\partial U'}{\partial x} d\eta'$$

$$\frac{\partial T'}{\partial t} = -\frac{RT^*}{C_v} \left(\frac{\partial U'}{\partial x} + d' \right)$$

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Linear equations σ -coor with orographic terms

$$\frac{\partial U'}{\partial t} = \dots + \frac{RT^*}{\pi_S^{*2}} \frac{\partial \pi_S^*}{\partial x} \pi'_S + \frac{1}{T^*} \frac{\partial \phi^*}{\partial x} T' - \frac{\partial \phi^*}{\partial x} q' - \frac{\pi^*}{m^*} \frac{\partial \phi^*}{\partial x} \frac{\partial q'}{\partial \eta}$$

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Linear equations η -coor with orographic terms

$$\frac{\partial U'}{\partial t} = \dots + R_d T^* \int_{\eta}^1 \frac{\partial}{\partial x} \left(\frac{m^*}{\pi^*} \right) q d\eta' - R_d \int_{\eta}^1 \frac{\partial}{\partial x} \left(\frac{m^*}{\pi^*} \right) T' d\eta'$$

$$\frac{\partial d'}{\partial t} = \dots$$

$$\frac{\partial q'}{\partial t} = \dots$$

$$\frac{\partial T'}{\partial t} = \dots$$

$$\frac{\partial \pi'_S}{\partial t} = \dots$$



Linear equations η -coord with orographic terms

In general :

$$\frac{\partial X}{\partial t} = L(X)$$

With a 2-TL discretisation :

$$\left[I - \frac{\delta t}{2} L \right] X^+ = X^\bullet$$



SI scheme

I	A	U^+	U^\bullet
B	C	d^+	d^\bullet
		q^+	q^\bullet
		T^+	T^\bullet
		π_S^+	π_S^\bullet

=



SI scheme

I	A	U^+	U^\bullet
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=



SI scheme

$$U^+ + A\Phi^+ = U^\bullet$$

$$BU^+ + C\Phi^+ = \Phi^\bullet$$

We can reduce the problem to only one equation :

$$\left[I - AC^{-1}B \right] U^+ = U^\bullet - AC^{-1}\Phi^\bullet$$



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- Orographic idealised test cases
- Identify the instability contribution of each orographic term



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Conclusion & perspectives

Scalability :

- Grid point approach seems viable in AROME
- Grid point approach seems competitive

Perspectives

- To test some preconditioners ?
- To remove completely spectral computations in AROME ?

Steep slopes :

Perspectives

- To test it in AROME 2D
- To measure the interest/potential



End

Thank you for your attention !

Do you have some questions ?



Linearisation

Constant coefficient approach :

$$\pi(x, \eta) = \pi^*(\eta) + \pi'(x, \eta)$$

where :

$$\pi^*(\eta) = A(\eta) + B(\eta)\pi_S^*$$

Linearisation around a state which contains **orography** :

$$\pi(x, \eta) = \pi^*(x, \eta) + \pi'(x, \eta)$$

where :

$$\pi^*(x, \eta) = A(\eta) + B(\eta)\pi_S^*(x)$$

In σ -coordinate : $A(\eta) = 0$, hence :

$$\frac{m^*}{\pi^*} = \frac{\partial_{\eta} B(\eta)\pi_S^*(x)}{B(\eta)\pi_S^*(x)} = \frac{\partial_{\eta} B(\eta)}{B(\eta)}$$



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C is a block diagonal matrix that contains $N_x N_y \approx 10^6$ blocks of matrix of size $N_L = 90$

Solution ? Some blocks are so similar that we can suppose they are identical, then we have to invert only few (1000 ?) blocks



Accélération de la convergence

$$Ax = b$$

est équivalent à :

$$PAx = Pb$$

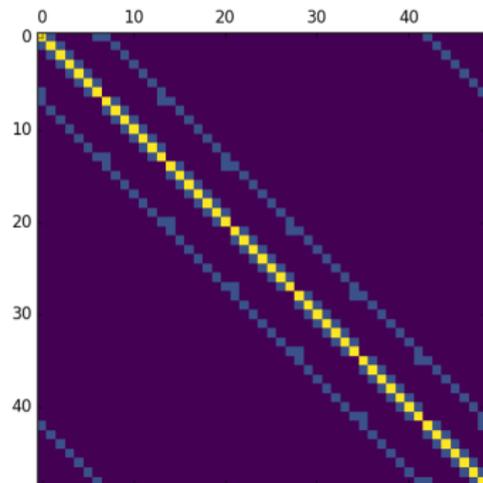
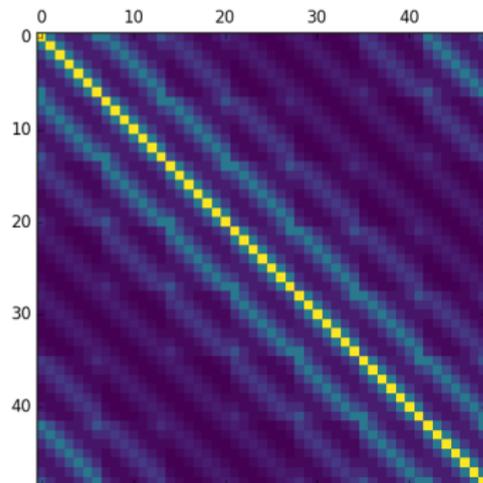
P est un bon préconditionneur si $P \approx A^{-1}$ ie :

- $\text{cond}(PA) \ll \text{cond}(A)$
- coût CPU faible du produit PA
- coût communication faible du produit PA



Méthode point de grille

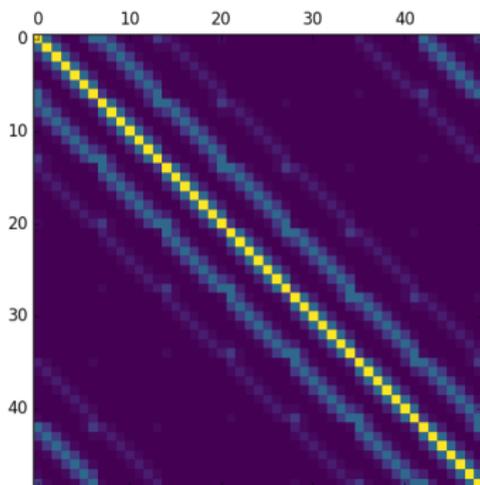
$$\text{cond}(A) = 262$$

 A  A^{-1}

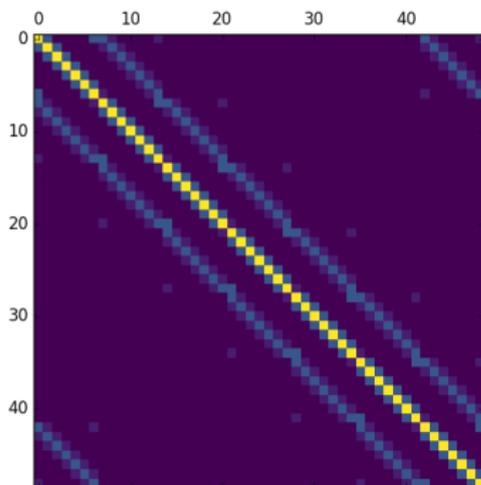


Préconditionneur

$$\text{cond}(A) = 262$$



$$\text{cond}(PA) = 31, \alpha = 47\%$$



$$\text{cond}(PA) = 55, \alpha = 7\%$$